



DX345, DX346, DX347 and DX348 Multifunction Indicators with Pulse Inputs

Operation modes:

- High Speed Position and Event Counter (100 kHz)
- Tachometer, Frequency Meter
- Baking Time and Processing Time Indicator (reciprocal speed)
- Timer, Stopwatch
- Speed Display from Transition Time between Start and Stop Impulse
- Additional Functions: Linearization, Brightness Control, Digital Filter etc.

Available devices:

- **DX345:** Speed and Rate Meter (display only)
- **DX346:** Speed and Rate Meter with analog output
- **DX347:** Speed and Rate Meter with 2 presets and transistor outputs
- **DX348:** Speed and Rate Meter with serial RS232 / RS485 interface

Version:	Description
DX34502/af/hk/July 03	Supplements for DX348 serial interface
DX34503/af/hk/Jan. 04	Range extensions and supplements for serial code
DX34504/hk/hk/Jan. 07	Version with 3 keys, A5 brochure, SV006, TTLIN, serial Reset
DX34508c/hk/hk/Mar08	Small modifications only
DX34509a/hk/kk/Jun09	Linearization, Manual Printing
DX34509b/sm/pp/Nov.11	Chapter 4.3 supplemented by "Response time of analog output"
DX34509c/pp/May12	Small modifications in chapter 4.1 : LrnodE
DX34510a/sn/Feb.13	Upgrading 4.2.3. Timer Stopwatch, Start / Stop: Loo.H I
Dx34510b_oi/ag/May15	<ul style="list-style-type: none"> - New Technical Specifications, Disclaimer, Safety Instructions and Design - Analog output notice (mA and V not usable at the same time) - Adjustment range numbers for serial parametrization via OS supplemented
Dx345_10c_oi/ag/Mar-16	Techn. Specifications: max. 15 kHz (all other modes)

Legal notices:

All contents included in this manual are protected by the terms of use and copyrights of motrona GmbH. Any reproduction, modification, usage or publication in other electronic and printed media as well as in the internet requires prior written authorization by motrona GmbH.

Table of Contents

1. Safety Instructions and Responsibility	5
1.1. General Safety Instructions.....	5
1.2. Use according to the intended purpose	5
1.3. Installation.....	6
1.4. Cleaning, Maintenance and Service Notes.....	6
2. Electrical Connections	7
2.1. Power Supply.....	8
2.2. Aux. Voltage Output	8
2.3. Inputs A, B and Reset.....	8
2.4. Adjustable Analog Output (DX 346 only).....	9
2.5. Optocoupler / Transistor Outputs (DX 347 only) *)	9
2.6. Serial RS232 / RS485 interface (DX 348 only).....	10
3. How to Operate the Front Keys	11
3.1. Normal Display State	11
3.2. Selection and Setting of Parameters	12
3.2.3. How to select a parameter	12
3.2.4. How to change parameter settings	12
3.2.5. How to store settings	12
3.2.6. Time-Out Function.....	12
3.3. Teach Operation	13
3.4. Set All Registers to "Default"	13
3.5. Code Locking of the Keypad.....	13
4. The Operator Menu	14
4.1. Overview of Basic Parameters	14
4.2. Overview of Operational Parameters.....	15
5. Setup Procedure	16
5.1. Basic Settings.....	16
5.2. Operational Parameters	18
5.2.1. RPM, operation as tachometer or frequency counter	18
5.2.2. Time, display of baking or processing time (reciprocal speed).....	19
5.2.3. Timer, Stopwatch.....	20
5.2.4. Count, Counter mode	21
5.2.5. Speed from differential time between a Start and a Stop input.....	22
5.2.6. Linearization points.....	22
5.3. Model DX 346: Additional Settings for the Analog Output	23
5.4. Model DX 347: Additional settings for Preselection's.....	25
5.5. Model DX 348: Additional Settings for the Serial Interface.....	27
5.5.1. PC-Mode.....	29
5.5.2. Printer-Mode	31

6. Special Functions.....	32
6.1. Linearization	32
6.2. Manual Input or „Teaching“ of the Interpolation Points.....	34
7. Technical Appendix	36
7.1. Dimensions	36
7.2. Technical Specifications	37
7.3. Parameter-List	38
7.3.3. General	38
7.3.4. Linearization.....	39
7.3.5. Analog Output (DX 346)	40
7.3.6. Preselection's (DX 347)	40
7.3.7. Serial interface (DX 348).....	40
7.4. Commissioning Form	41

1. Safety Instructions and Responsibility

1.1. General Safety Instructions

This operation manual is a significant component of the unit and includes important rules and hints about the installation, function and usage. Non-observance can result in damage and/or impairment of the functions to the unit or the machine or even in injury to persons using the equipment!

Please read the following instructions carefully before operating the device and observe all safety and warning instructions! Keep the manual for later use.

A pertinent qualification of the respective staff is a fundamental requirement in order to use these manual. The unit must be installed, connected and put into operation by a qualified electrician.

Liability exclusion: The manufacturer is not liable for personal injury and/or damage to property and for consequential damage, due to incorrect handling, installation and operation. Further claims, due to errors in the operation manual as well as misinterpretations are excluded from liability.

In addition the manufacturer reserve the right to modify the hardware, software or operation manual at any time and without prior notice. Therefore, there might be minor differences between the unit and the descriptions in operation manual.

The raiser respectively positioner is exclusively responsible for the safety of the system and equipment where the unit will be integrated.

During installation or maintenance all general and also all country- and application-specific safety rules and standards must be observed.

If the device is used in processes, where a failure or faulty operation could damage the system or injure persons, appropriate precautions to avoid such consequences must be taken.

1.2. Use according to the intended purpose

The unit is intended exclusively for use in industrial machines, constructions and systems. Non-conforming usage does not correspond to the provisions and lies within the sole responsibility of the user. The manufacturer is not liable for damages which has arisen through unsuitable and improper use.

Please note that device may only be installed in proper form and used in a technically perfect condition (in accordance to the Technical Specifications). The device is not suitable for operation in explosion-proof areas or areas which are excluded by the EN 61010-1 standard.

1.3. Installation

The device is only allowed to be installed and operated within the permissible temperature range. Please ensure an adequate ventilation and avoid all direct contact between the device and hot or aggressive gases and liquids.

Before installation or maintenance, the unit must be disconnected from all voltage-sources. Further it must be ensured that no danger can arise by touching the disconnected voltage-sources.

Devices which are supplied by AC-voltages, must be connected exclusively by switches, respectively circuit-breakers with the low voltage network. The switch or circuit-breaker must be placed as near as possible to the device and further indicated as separator.

Incoming as well as outgoing wires and wires for extra low voltages (ELV) must be separated from dangerous electrical cables (SELV circuits) by using a double resp. increased isolation.

All selected wires and isolations must be conform to the provided voltage- and temperature-ranges. Further all country- and application-specific standards, which are relevant for structure, form and quality of the wires, must be ensured. Indications about the permissible wire cross-sections for wiring are described in the Technical Specifications.

Before first start-up it must be ensured that all connections and wires are firmly seated and secured in the screw terminals. All (inclusively unused) terminals must be fastened by turning the relevant screws clockwise up to the stop.

Overvoltages at the connections must be limited to values in accordance to the overvoltage category II.

For placement, wiring, environmental conditions as well as shielding and earthing/grounding of the supply lines the general standards of industrial automation industry and the specific shielding instructions of the manufacturer are valid. Please find all respective hints and rules on www.motrona.com/download.html --> "[General EMC Rules for Wiring, Screening and Earthing]".

1.4. Cleaning, Maintenance and Service Notes

To clean the front of the unit please use only a slightly damp (not wet!), soft cloth. For the rear no cleaning is necessary. For an unscheduled, individual cleaning of the rear the maintenance staff or assembler is self-responsible.

During normal operation no maintenance is necessary. In case of unexpected problems, failures or malfunctions the device must be shipped for back to the manufacturer for checking, adjustment and reparation (if necessary). Unauthorized opening and repairing can have negative effects or failures to the protection-measures of the unit.

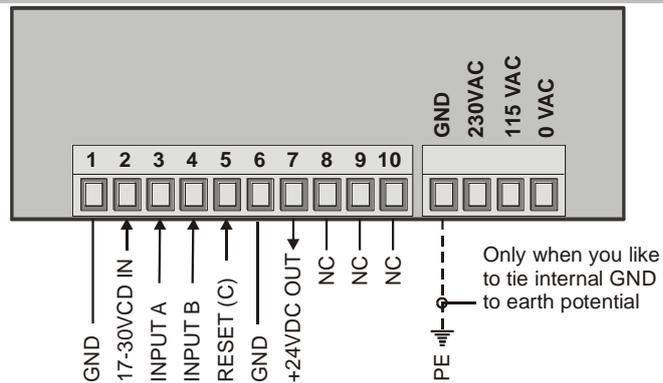
2. Electrical Connections

DX345:

Display unit only

Special versions with TTL inputs (option TTLIN1) provide a +5V aux. output on terminal 7, instead of +24V

Units with option SV006 provide 24 / 42 VAC power input instead of 115 / 230 VAC

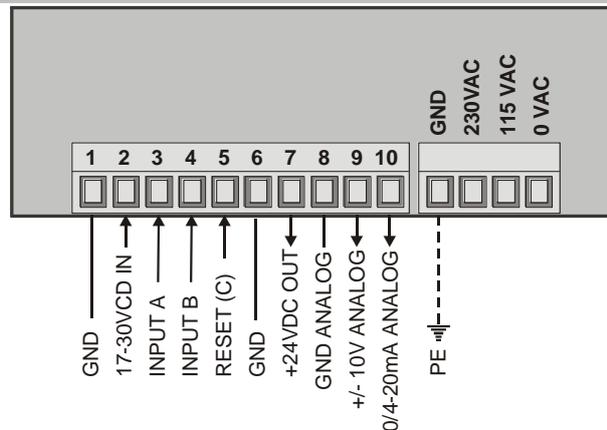


DX 346:

Display unit with analog output

Special versions with TTL inputs (option TTLIN1) provide a +5V aux. output on terminal 7, instead of +24V

Units with option SV006 provide 24 / 42 VAC power input instead of 115 / 230 VAC

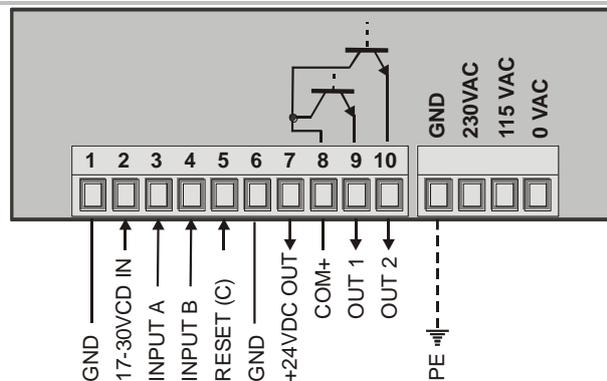


DX347:

Display unit with 2 presets and transistor outputs

Special versions with TTL inputs (option TTLIN1) provide a +5V aux. output on terminal 7, instead of +24V

Units with option SV006 provide 24 / 42 VAC power input instead of 115 / 230 VAC

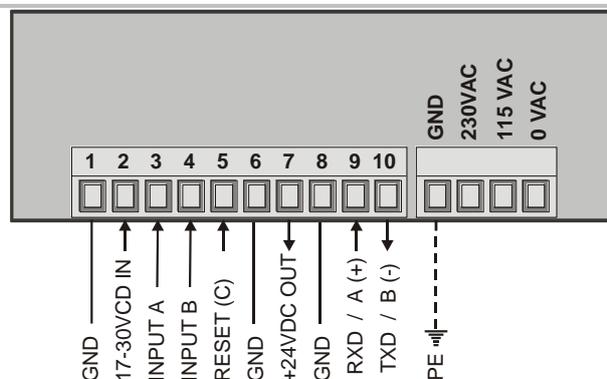


DX348:

Display unit with serial interface

Special versions with TTL inputs (option TTLIN1) provide a +5V aux. output on terminal 7, instead of +24V

Units with option SV006 provide 24 / 42 VAC power input instead of 115 / 230 VAC



2.1. Power Supply

The unit accepts DC supply from 17 V to 30 V when using terminals 1 and 2, and the consumption depends on the level of the supply voltage (typically between 80 mA and 150 mA plus current taken from aux. output).

For AC supply, terminals 0 VAC, 115 VAC or 230 VAC can be used. The total AC power consumption is 7.5 VA.

Units with option "SV006" are prepared for AC supply with 24 VAC or 42 VAC and the screw terminals are marked correspondingly.

The diagrams show a dotted line for grounding to PE. This connection is not necessary, neither for safety nor for EMC. However, with specific applications, it can be useful to ground the common potential of all signal lines.



When using this earthing option, please observe:

- All terminals and potentials marked "GND" will be earthed.
- You should avoid multiple earthing, e.g. when you use a DC power supply where the Minus is already connected to earth etc. Especially under poor earthing and grounding conditions, multiple earth connections may cause serious EMC problems.

2.2. Aux. Voltage Output

Terminal 7 provides an auxiliary output of 24 VDC / 120 mA max. for supply of sensors and encoders. Units with TTL inputs (option TTLIN1) provide a 5 VDC / 120 mA auxiliary output on terminal 7 instead.

2.3. Inputs A, B and Reset

In the basic setup menu these inputs can be configured to PNP (switch to +) or to NPN (switch to -). This configuration is valid for all three inputs at a time.

The factory setting is always PNP.

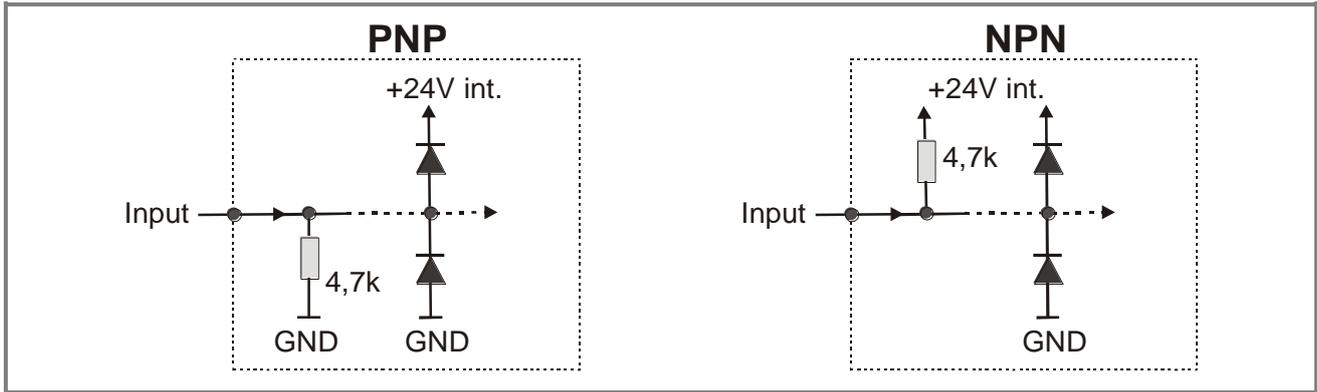
With standard units the input level is always HTL (Low <2.0 V and High >9.0 V)

Units equipped with option TTLIN1 provide TTL / CMOS) level (Low <0.8 V and High >3.5 V)



- Independent of your setting, all functions of the unit are "active HIGH" and the unit triggers to positive transitions (rising edge).
- With NPN setting please be aware that an open or unused RESET input is HIGH. Therefore the unit will be kept in a continuous RESET state and will not work, unless you tie the Reset line to GND (terminal 1 or 6)
- Where your use 2-wire NAMUR type sensors, please select NPN, connect the negative wire of the sensor to GND and the positive wire to the corresponding input.

Typical input circuit (standard version with HTL inputs):



The counting inputs A and B are designed for input frequencies up to 100 kHz (with all counter modes) and up to 15 kHz (with all other operating modes). The minimum pulse duration on the Reset input must be 500 μ sec. (maximum frequency 1 kHz). All inputs are designed to receive impulses from an electronic impulse source. Where exceptionally you need to **use mechanical contacts**, please connect an external capacitor between GND (-) and the corresponding input (+). With a capacity of 10 μ F, the maximum input frequency will reduce to 20 Hz and miscounting due to contact bouncing will be eliminated.

2.4. Adjustable Analog Output (DX 346 only)

A voltage output is available, operating in a range of 0 ... +10 V or -10 V ... +10 V according to setting. At the same time, a current output 0/4 ... 20 mA is available. Both outputs refer to the GND potential and the signal polarity changes with the sign in the display.

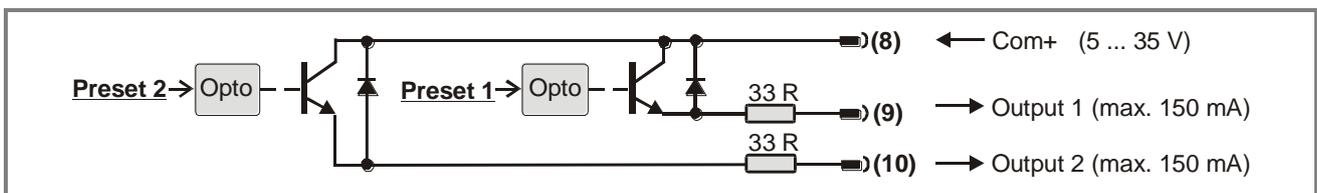
The outputs provide a 14 bits resolution and the response time to changes of the measuring value is approx. 7 msec. ($f_{in} > 143$ Hz). The maximum current of the voltage output is 2 mA, and the load on the current output can vary between 0 and max. 270 ohms.



Important note: "Voltage out" and "Current out" cannot be used together. Please do never connect mA and V simultaneously!

2.5. Optocoupler / Transistor Outputs (DX 347 only) *)

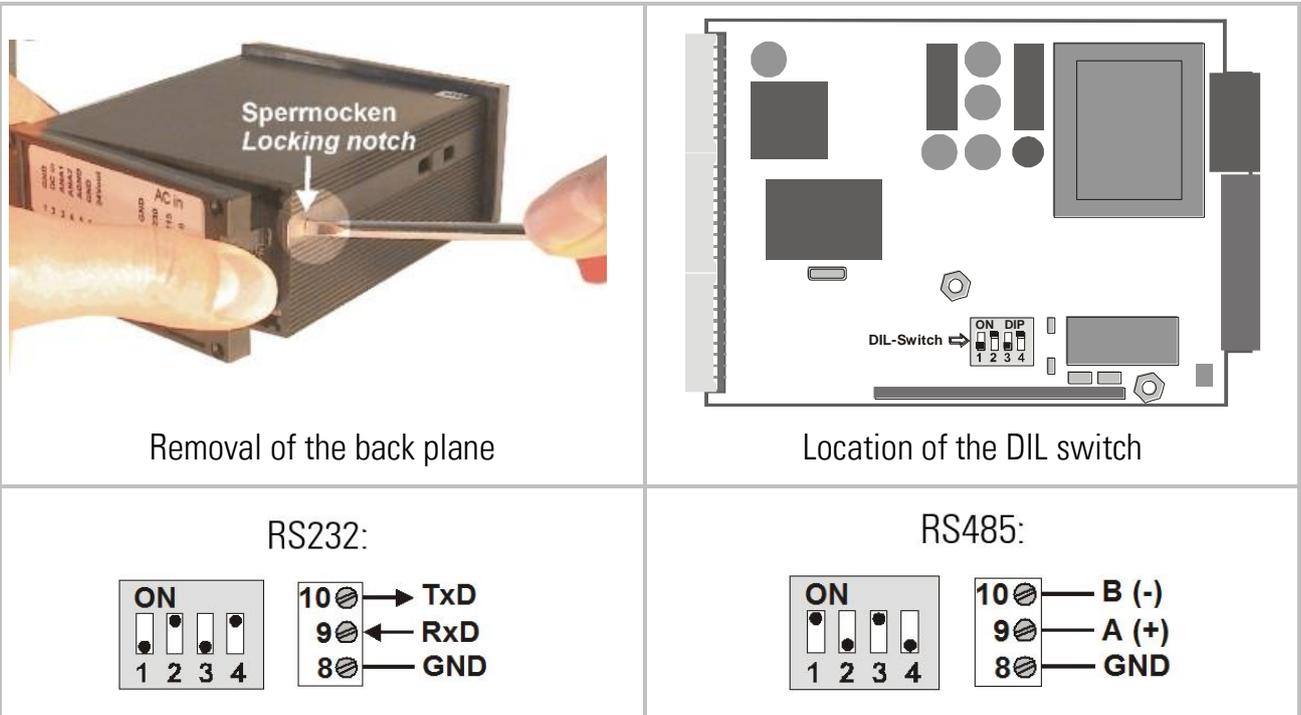
The outputs provide programmable switching characteristics and are potential-free. Please connect terminal 8 (COM+) to the positive potential of the voltage you like to switch (range 5V...30V). You must not exceed the maximum output current of 150 mA. Where you switch inductive loads, please provide filtering of the coil by means of an external diode.



*) For relay outputs please refer to model DX342

2.6. Serial RS232 / RS485 interface (DX 348 only)

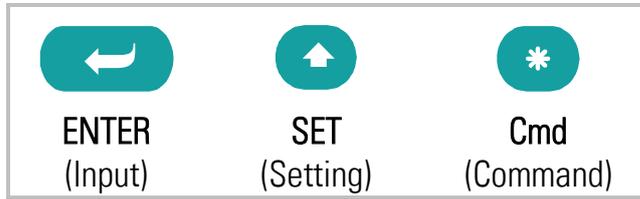
Ex-factory the unit is set to RS232 communication. This setting can be changed to RS485 (2-wire) by means of an internal DIL switch. To access the DIL switch, please remove the screw terminal connectors and the backplane. Then pull the print to the rear to remove the PCB from the housing.



- Never set DIL switch positions 1 and 2 or DIL switch positions 3 and 4 to ON at the same time!
- After setting the switch, shift the print carefully back to the housing, in order to avoid damage of the front pins for connection with the front plate.

3. How to Operate the Front Keys

For setup and other operations the unit uses three front keys which subsequently will be denominated as follows:



The functions of the keys are depending on the actual operating state of the unit. The following three operating states apply:

- Normal display state
- Setup state
 - a.) Basic setup
 - b.) Operational parameter setup
- Teach operation

3.1. Normal Display State



You can only change over to other operation states while the unit is in display state.

Change over to	Key operation
Basic setup	Keep ENTER and SET down simultaneously for 3 seconds
Operational parameter setup	Keep ENTER down for 3 seconds.
Teach operation	Keep Cmd down for 3 seconds

The Cmd key is only used to execute the Teach procedure with linearization. For more details please refer to sections [5.1](#) and [5.2](#).

3.2. Selection and Setting of Parameters

3.2.3. How to select a parameter

The **ENTER** key will scroll through the menu. The **SET** key allows to select the corresponding item and to change the setting or the numeric value. After this, the selection can be stored by **ENTER** again, which automatically changes over to the next menu item.

3.2.4. How to change parameter settings

With numerical entries, at first the lowest digit will blink. When keeping the **SET** key continuously down, the highlighted digit will scroll in a continuous loop from 0 ... 9, 0 ... 9. After releasing the **SET** key, the actual value will remain and the next digit will be highlighted (blink). This procedure allows setting of all digits to the desired values. After the most significant digit has been set, the low order digit will blink again and you can do corrections if necessary.

With signed parameters, the high order digit will scroll from "0" to "9" (positive) followed by "-" and "-1" (negative)

3.2.5. How to store settings

To store the actual setting, press the **ENTER** key, which will also automatically scroll forward the menu.

At any time the unit changes from programming mode to normal display operation, when you keep the **ENTER** key down again for at least 3 seconds.

3.2.6. Time-Out Function

A "time-out" function will automatically conclude every menu level, when for a break period of 10 seconds no key has been touched. In this case, all changes which have not been confirmed by **ENTER** yet would remain unconsidered.

3.3. Teach Operation



The Time-Out Function remains disabled during all Teach operations

Key	Function
	ENTER will conclude or abort any Teach operation in progress
	SET function is fully similar to normal set-up operation
	Cmd will store the display value to the register and will change over to the next interpolation point.

For details of the Teach procedure see section [5.2](#).

3.4. Set All Registers to “Default”

At any time you can return all settings to the factory default values.



This action will reset all parameters to factory default values and your own settings will be lost. You will have to repeat your individual setup procedure. Factory default values are shown in the subsequent parameter tables.

To reset the unit to default values:

- switch power off
- press the ENTER key on the front
- keep ENTER down while you power up again

3.5. Code Locking of the Keypad

When the code locking of the keypad has been switched on, any key access first results in display of



To access the menu you must press the key sequence



within 10 seconds, otherwise the unit will automatically return to the normal display mode.

4. The Operator Menu

The menu provides one section with "Basic Parameters" and another section with "Operational Parameters". On the display you will only find those parameters which have been enabled by the basic settings. E.g. when the Linearisation Function has been disabled in the basic set-up, the associated linearization parameters will also not appear in the parameter menu.

All parameters, as good as possible, are designated by text fragments. Even though the possibilities of forming texts are very limited with a 7-segment display, this method has proved to be most suitable for simplification of the programming procedure.

The subsequent table shows the general structure of the menu.

Detailed descriptions of all parameters will follow in section [5.2](#).

4.1. Overview of Basic Parameters

DX345	DX346	DX347	DX348
Type (Application Mode)	Type (Application Mode)	Type (Application Mode)	Type (Application Mode)
Input Characteristics	Input Characteristics	Input Characteristics	Input Characteristics
Brightness	Brightness	Brightness	Brightness
Code	Code	Code	Code
Linearization Mode *)	Linearization Mode *)	Linearization Mode *)	Linearization Mode *)
	Analog Output Mode	Preselection Mode 1	Serial Unit Number
	Analog Offset	Preselection Mode 2	Serial Format
	Analog Gain	Hysteresis 1	Serial Baud Rate
		Hysteresis 2	

*) Appears only with Modes "RPM" and "Count"

4.2. Overview of Operational Parameters

	Mode "RPM" (Tachometer)	Mode "Time" (Baking Time)	Mode "Timer" (Stopwatch)	Mode "Count" (Counter)	Mode "Speed" (Transition speed)	
DX345	Frequency	Display Format	Base (Resolution)	Counter Mode	Time	
	Display Value	Frequency	Start/Stop	Scaling Factor	Display Value	
	Decimal Point	Decimal Value	Auto Reset	Set Value	Decimal Point	
	Wait Time	Wait Time	Latch Function	Reset/Set	Wait Time	
	Average Filter	Average Filer		Decimal Point		
DX346	Frequency	Display Format	Base (Resolution)	Counter Mode	Time	
	Display Value	Frequency	Start/Stop	Scaling Factor	Display Value	
	Decimal Point	Decimal Value	Auto Reset	Set Value	Decimal Point	
	Wait Time	Wait Time	Latch Function	Reset/Set	Wait Time	
	Average Filter	Average Filer		Decimal Point		
				Analog Begin		
				Analog End		
DX347	Preselection 1					
	Preselection 2					
	Frequency	Display Format	Base (Resolution)	Counter Mode	Time	
	Display Value	Frequency	Start/Stop	Scaling Factor	Display Value	
	Decimal Point	Decimal Value	Auto Reset	Set Value	Decimal Point	
	Wait Time	Wait Time	Latch Function	Reset/Set	Wait Time	
	Average Filter	Average Filer		Decimal Point		
DX348	Frequency	Display Format	Base (Resolution)	Counter Mode	Time	
	Display Value	Frequency	Start/Stop	Scaling Factor	Display Value	
	Decimal Point	Decimal Value	Auto Reset	Set Value	Decimal Point	
	Wait Time	Wait Time	Latch Function	Reset/Set	Wait Time	
	Average Filter	Average Filer		Decimal Point		
	Serial Timer					
	Serial Mode					
	Serial Code					
All units	P01_H(*)			P01_H(*)		
	P01_Y(*)			P01_Y(*)		
		
	P16_H(*)			P16_H(*)		
	P16_Y(*)			P16_Y(*)		

*) Appears only with modes "RPM" and "Count" when the linearization function has been enabled

5. Setup Procedure

For better understanding the following sections 4.1 and 4.2 explain settings related to the display only. Model-specific settings for Analog Output, Preselection's and Serial Link will be explained separately under sections [5.3](#) to [5.5](#), later.

5.1. Basic Settings

These settings in general have to be carried out one time only upon the very first use of the unit. The basic setup selects the desired operation mode of the unit, the input characteristics PNP/NPN and the desired brightness of the LED display.



To access the Basic Setup press ENTER and SET simultaneously for at least 3 seconds.

Menu		Setting Range	Default
TYPE	Operation Mode: Tachometer, frequency meter (5.2.1) Baking time / processing time indicator (5.2.2) Timer, Stopwatch (5.2.3) Counter for position or event (5.2.4) Speed calculation from differential transition time (5.2.5)	<input type="text" value="rPn"/> <input type="text" value="זרתז"/> <input type="text" value="זרתזר"/> <input type="text" value="Count"/> <input type="text" value="SPEED"/>	<input type="text" value="rPn"/>
CHAR	Switching characteristics of the inputs: NPN, switch to "-" PNP, switch to "+"	<input type="text" value="nPN"/> <input type="text" value="PNP"/>	<input type="text" value="PNP"/>
br .Ght	Brightness of the LED display:	20%, 40%, 60%, 80%, 100%	100%

Continuation "Basic Settings"

Menu		Setting Range	Default
Code	<p>Keypad protection code: (see section 3.5)</p> <p>Keypad enabled continuously</p> <p>Keypad locked for any access</p> <p>Keypad locked, except for access to preselection's Pres 1 und Pres 2 (DX 347 only)</p>	<p>no</p> <p>ALL</p> <p>P_FREE</p>	<p>no</p>
Lmode	<p>Linearization Mode: *) For details please refer to 5.1 and 5.2</p> <p>The linearization is switch off.</p> <p>Linearization settings for the positive range only (negative values will appear as a mirror).</p> <p>Linearization over the full numeric range</p>	<p>no</p> <p>1-9UR</p> <p>4-9UR</p>	<p>no</p>

*) with Tachometer mode and Counter mode only

5.2. Operational Parameters

5.2.1. RPM, operation as tachometer or frequency counter

(Input A = active input, Input B not in use), (only DX346: Input B = active input)

Menu		Range (OS)*	Default
FREQ	Frequency: Set a typical operating frequency for your application.	1 Hz to 25 000 Hz	1000
DISP	Display Value: Set the value you would like to see on your display with above frequency at the input.	1 ... 99999	1000
DPo int	Decimal Point: Select the desired position like shown in the display. no decimal point decimal point at position 1 ----> decimal point at position 5	000000 00000.0 0.00000	000.000
WAIT	Wait Time: Define a "waiting time", this is the time in seconds that the unit will wait from one input pulse to the next, before it sets the display to zero. When you enter "0", the unit will wait forever and show the last result until it receives the next input.  The setting of this parameter automatically limits the minimum input frequency correspondingly. With "Wait" set to e.g. 0.1 sec. the unit will respond to frequencies > 10 Hz only and all lower frequencies will just display 0.	0.1 ... 99.9 sec	1.0
FILTER	Average Filter: Selectable average filter to suppress unstable display with unsteady input frequencies. No filtering 2, 4, 8, 16 = number of floating average cycles.	OFF (0) 16 (1)	OFF

*) OS only with DX348



Model DX346 also provides a signed speed display with the +/- sign changing according to the direction of rotation. To indicate the direction in the display by a sign, +/- 10 V must be adjusted in the analog menu (see section [5.3](#)).

5.2.2. Time, display of baking or processing time (reciprocal speed)

(Input A = frequency input, Input B not in use)

Menu		Range (OS)*	Default
d ,Sfor	<p>Display Format: Select between seconds, minutes, minutes and seconds or minutes with two decimal positions. This will also automatically set your decimal point to the proper place.</p> <p>Seconds</p> <p>Minutes</p> <p>Minutes and seconds</p> <p>Minutes with two decimal positions</p>	<p>SEC (0)</p> <p>ה ד ה (1)</p> <p>ה ד ,SE (2)</p> <p>ה ד ה .00 (3)</p>	SEC
FrEQ	<p>Frequency: Set a typical operating frequency for your application.</p>	1 Hz to 25 000 Hz	100
d ,SPL	<p>Display Value: Set the value you would like to see on your display with above frequency at the input.</p>	1 ... 999999	100
LJA t	<p>Wait Time: Define a "waiting time", this is the time in seconds that the unit will wait from one input pulse to the next, before it sets the display to zero. When you enter "0", the unit will wait forever and show the last result until it receives the next input.</p> <p> The setting of this parameter automatically limits the minimum input frequency correspondingly. With "Wait" set to e.g. 0.1 sec. the unit will respond to frequencies > 10 Hz only and all lower frequencies will just display 0.</p>	0.1 ... 99.9 s	5.0
F ilteR	<p>Average Filter Selectable averages filter to suppress unstable display with unsteady input frequencies.</p> <p>No filtering</p> <p>2, 4, 8, 16 = number of floating average cycles.</p>	<p>OFF (0)</p> <p>16 (1)</p>	OFF

*) OS only with DX348

5.2.3. Timer, Stopwatch

Please note that open NPN inputs are always "HIGH" and open PNP inputs are always "LOW".

Menu		Range (OS)*	Default
BASE	Time base / Resolution of the timer: Milliseconds 1/100 seconds 1/10 seconds Integer seconds Minutes with two decimal positions Minutes with one decimal position Hours : minutes : seconds	SECO00 (0) SECO0 (1) SECO (2) SEC (3) mm.00 (4) mm.0 (5) H-mm-S (6)	SECO00
StArt	Start/Stop of time measurement: Time count is active while input A is HIGH. Rising edge on input A starts count. Rising edge on input B stops count. Period time measurement. Repeating display of the time between two rising edges on input A	H ,_Loo (0) St_SP (1) A_StSP (2)	St_SP
	Time count is active while input A is LOW.	Loo_H ,	
rESEt	Auto Reset: Time count cumulates with every new start. No automatic Reset. Use the Reset input to set to zero. Every start initializes a new count starting from zero.	no (0) YES (1)	no
LRtch	Latch Function: Real time display, count visible. Frozen display of the final count result after every Stop. The timer counts in the background,	no (0) YES (1)	no

*) OS only with DX348

5.2.4. Count, Counter mode

Menu		Range (OS)*	Default
MODE	Counting Mode: Input A counts and input B selects the counting direction (LOW = increment, HIGH = decrement) Summing counter, A + B Differential counter, A – B Quadrature up/down counter A/B with single edge count (x1) Quadrature up/down counter A/B with double edge count (x2) Quadrature up/down counter A/B with (x4) edge count.	A_b d r (0) A + b (1) A - b (2) A_b .1 (3) A_b 2 (4) A_b 4 (5)	A_b .1
FACTOR	Impulse Scaling Factor: Example: setting 1.2345 results in display of 12 345 after 10 000 input pulses.	0.0001 ... 9.9999	1.0000
SET	Set Value: Every Reset signal will set the display to the value entered here	-199 999 ... 999 999	0
RESET	Reset/Set Enable: No setting or resetting of the counter is possible Set / Reset by the front SET key Set / Reset by remote signal to the Reset input. Set / Reset by front SET key and by external input.	no (0) front (1) ExtErn (2) Fr u E (3)	Fr u E
dPo int	Decimal Point: Select the desired position like shown in the display. no decimal point one decimal position ----> five decimal positions	000000 00000.0 0.00000	000.000

*) OS only with DX348



- The counting range of the unit is limited from -199999 to 999999.
In case of underflow or overflow the unit will display **-----**
- The counter stores all counting data also in power-down state (EEPROM with data retention >10 years)
- With the summing mode (A+B) and the differential mode (A-B) please note that the impulse scaling factor will only affect input A

5.2.5. Speed from differential time between a Start and a Stop input

Input A operates as a start input and input B operates as a Stop input. The differential time between start and stop will be converted into the speed of the passing object.

Menu		Setting Range	Default
Time	Time: Enter a typical delay time which you expect between the start and stop signals.	000.001 ... 999.999 sec	1.000 sec
d.SPL	Display Value: Enter the speed you would like to see in the display when an object passes within above time.	000.001 ... 999.999	1.000
dPo int	Decimal Point: Select the desired position like shown in the display. no decimal point done decimal position ----> five decimal positions	000000 00000.0 0.00000	000.000
LJA t	Wait Time How long should the last result remain in the display before it returns to zero? Set the desired waiting time. With setting "0" the display will freeze and wait until to the next measuring cycle.	0.00 ... 9.99	1.00

5.2.6. Linearization points

The linearization points will only appear with Operation Modes "RPM" or "Count" when Linearization is enabled.

Menu		Setting Range	Default
P01_X	Linearization point 1: X value of the first interpolation point.	-199999 ... 999999	999999
P01_Y	Linearization point 1: Y value of the first interpolation point.	-199999 ... 999999	999999
	...		
	...		
P16_X	Linearization point 16: X value of the 16. interpolation point.	-199999 ... 999999	999999
P16_Y	Linearization point 16: Y value of the 16. interpolation point.	-199999 ... 999999	999999

For more details about linearization please refer to section [6.1](#)

5.3. Model DX 346: Additional Settings for the Analog Output

The Basic Menu provides the following additional settings:

Menu		Range (OS)**	Default
A-CHAR	Analog Characteristics: Select one of the following options: +/-10 V (bipolar) 0-10 V (positive output only) 4-20 mA current output. 0-20 mA current output Where you set the output to +/-10 Volts, your input signals A/B must be of quadrature type with phase displacement. The polarity of the output follows the sign in the display (operation as a counter or as a speed display with detection of direction of rotation)	- 10 _ 10 (0) 0 _ 10 (1) 4 _ 20 (2) 0 _ 20 (3)	0 _ 10
OFFSET	Analog Offset *): Set this register to "0" when your output range should begin at zero (or 4 mA) If you desire another initial output value, set this register correspondingly. Setting 5.000 means your output will start at 5 Volts instead of zero.	-9.999 ... +9.999	0.000
GAIN	Analog Gain *): Set the analog stroke you desire: Setting 1000 means 10 Volts or 20 mA. Setting 200 reduces the stroke to 2 Volts or 4 mA.	00.00 ... 99.99	10.00

*) see also next page

***) OS only with DX348

Response time of the analog output:

Operation mode	Response time analog output
Tachometer, frequency meter (5.2.1)	330ms at f >3Hz 1/f at f < 3Hz
Baking time / processing time indicator (5.2.1)	330ms at f >3Hz 1/f at f < 3Hz
Timer, Stopwatch (5.2.3)	7 ms (With latch function after every measurement)
Counter for position or event (5.2.4)	Counter value + 7ms
Speed calculation from differential transition time (5.2.5)	Runtime + 7ms

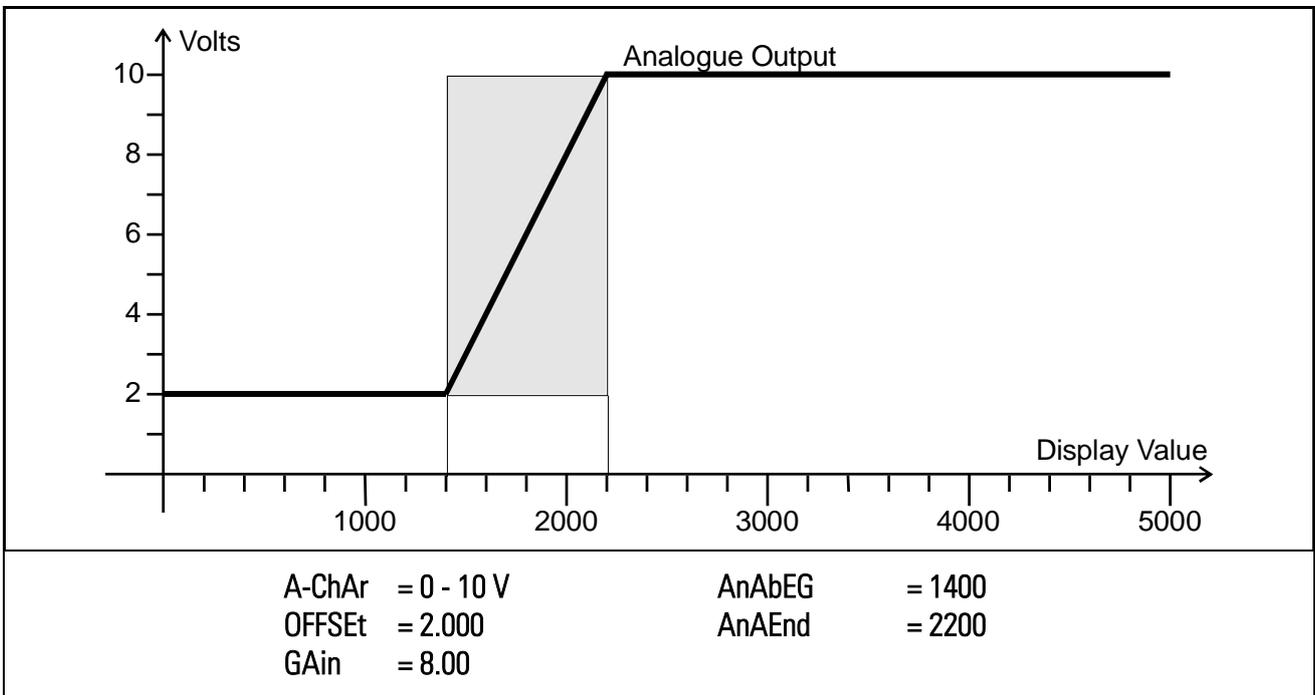
The analog output behaves like the display output.

The following Operational Parameters provide scaling of the analog output:

Menu		Setting Range	Default
AnAbEG	Analog-Begin: Start value of the analog output.	-199999 ... 999999	0
AnAEnd	Analog-End: End value of the analog output.	-199999 ... 999999	10000

By means of these two parameters any window of the whole display range can be mapped onto the analog output.

The subsequent example shows how to convert the display range from 1400 to 2200 into an analog signal of 2 - 10 volts.



All settings refer to the scaled values which are shown in the display of the unit.

5.4. Model DX 347: Additional settings for Preselection's

The basic setup menu provides the following additional parameters:

Menu	Range (OS)****	Default
CHAR 1	Switching characteristics of output 1.	--r GE
	--r GE (0) Greater/Equal: output to switch statically "ON" when display value \geq preset value.	
	--r LE (1) Lower/Equal: output to switch statically "ON" when display value \leq preset value.	
	n GE (2) Greater/Equal: output to switch dynamically "ON" when display value \geq preset value. (timed pulse output *)	
	n LE (3) Lower/Equal: output to switch dynamically "ON" when display value \leq preset value. (timed pulse output *)	
	RES (4) Reset: Timed impulse output *) and automatic Reset to zero when the display value reaches Preset 1.	
	_n_SEt (5) Set: Timed impulse output *) and automatic setting to preset 1 when the display value reaches zero.	
CHAR 2	Switching characteristics of output 2.	--r GE
	--r GE (0) See Char 1	
	--r LE (1) See Char 1	
	n GE (2) See Char 1	
	n LE (3) See Char 1	
	_J 1-2 (4) Output switches statically ON when display value \geq <u>Preset 1 – Preset 2</u> **).	
	_n 1-2 (5) Output switches dynamically ON when display value \geq <u>Preset 1 – Preset 2</u> **).	
HYS1	Hysteresis 1: Adjustable hysteresis for output 1. ***) Setting range 0 ... 99999 display units	0
HYS2	Hysteresis 2: Adjustable hysteresis for output 2, ***) Setting range 0 ... 99999 display units	0

*) Fixed pulse duration of 500 msec (factory adjustable only)

**) This feature serves for generation of an anticipation signal with a fixed distance to the preset 1 signal. The anticipation automatically follows the setting of preset 1 (trailing preset).

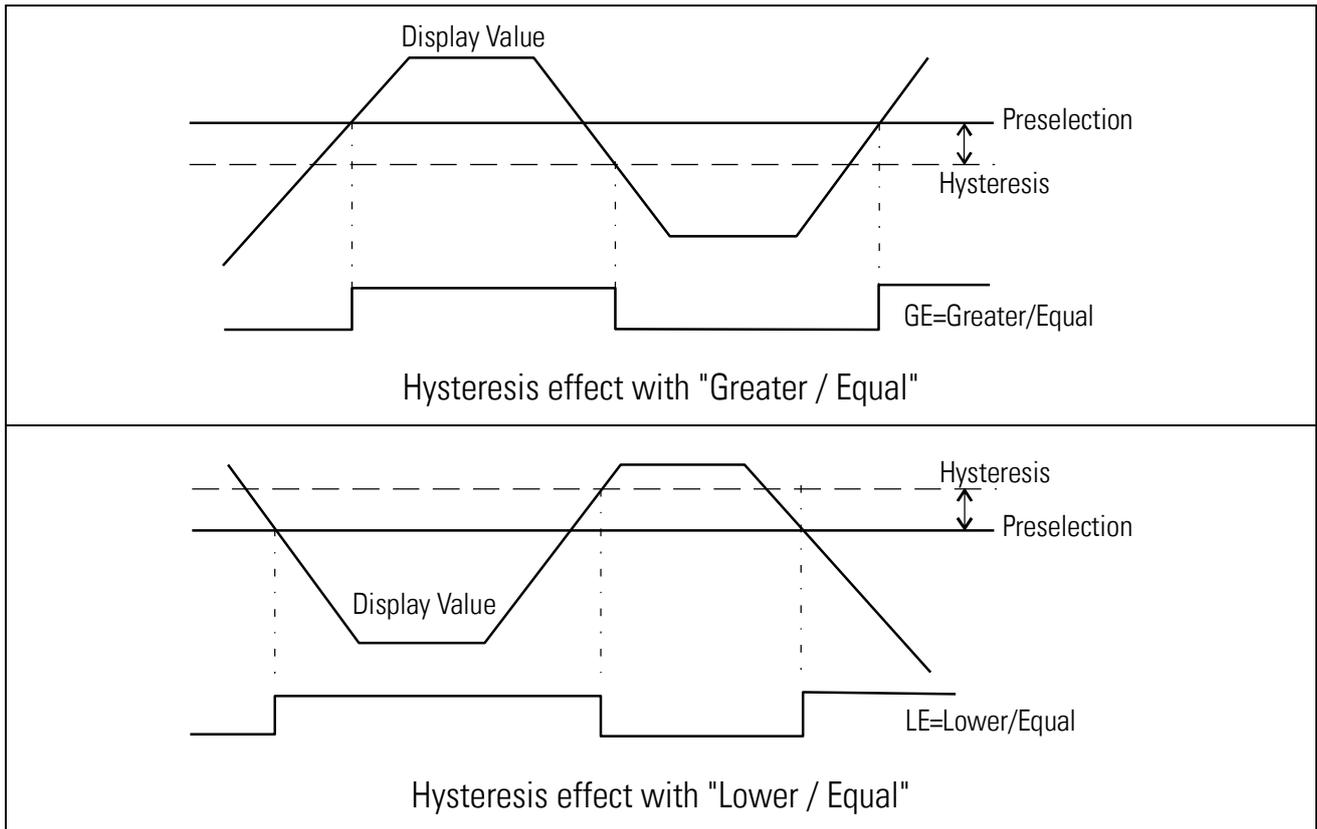
***) Switching hysteresis is only active with "RPM" and "Time" operation

****) OS only with DX348

The following operational parameters provide setting of the switching points:

Menu		Setting Range	Default
PrES_1	Preselection 1:	-199999... 999999	10000
PrES_2	Preselection 2:	-199999... 999999	5000

The working direction of the Hysteresis depends on the setting of the switching characteristics. With settings „GE“ or „LE“ respectively, the following switch points will result:



It is possible to check up on the actual switching state of the outputs at any time.

For this, just tap on the ENTER key shortly.

The display will then show for the next two seconds one of the following information:

Display	Meaning
1.2off	Both outputs are actually off.
1.2on	Both outputs are actually on.
1 on	Output 1 is on. Output 2 is off.
2on	Output 1 is off. Output 2 is on.

5.5. Model DX 348: Additional Settings for the Serial Interface

The basic setup menu contains the main parameters for configuration of the serial interface

Menu		Range (OS)*	Default
S-Unit	Serial Unit Number: You can assign any address number between 11 and 99 to your unit. The address must <u>not</u> contain a "0" because these numbers are reserved for collective addressing.	0 ... 99	11
S-Form	Serial data format: The first character indicates the number of Data Bits. The second character specifies the Parity Bit ("even" or "odd" or "none") The third character indicates the number of Stop Bits.	<div style="display: flex; flex-direction: column; gap: 5px;"> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 E 1 (0)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 E 2 (1)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 0 1 (2)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 0 2 (3)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 no 1 (4)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">7 no 2 (5)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">8 E 1 (6)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">8 0 1 (7)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">8 no 1 (8)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">8 no 2 (9)</div> </div>	7 E 1
S-bAUD	Baud Rate: The adjoining Baud rates can be selected	<div style="display: flex; flex-direction: column; gap: 5px;"> <div style="border: 1px solid black; padding: 2px; display: inline-block;">9600 (0)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">4800 (1)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">2400 (2)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1200 (3)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">600 (4)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">19200 (5)</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">38400 (6)</div> </div>	9600

*) OS only with DX348

The following operational parameters provide setting of the communication profile:

Menu		Range (OS)*	Default																
5-6 777	<p>Serial Timer: Setting 0,000 allows manual activation of a serial data transmission at any time. All other settings specify the cycle time for automatic transmission (provided the Serial Mode is set to "Printer")</p> <p>Between two transmission cycles the unit will allow a pause depending on the baud rate. The minimum cycle times for timer transmissions are shown in the table.</p> <table border="1"> <thead> <tr> <th>Baud Rate</th> <th>Minimum Cycle Time [msec]</th> </tr> </thead> <tbody> <tr><td>600</td><td>384</td></tr> <tr><td>1200</td><td>192</td></tr> <tr><td>2400</td><td>96</td></tr> <tr><td>4800</td><td>48</td></tr> <tr><td>9600</td><td>24</td></tr> <tr><td>19200</td><td>12</td></tr> <tr><td>38400</td><td>6</td></tr> </tbody> </table>	Baud Rate	Minimum Cycle Time [msec]	600	384	1200	192	2400	96	4800	48	9600	24	19200	12	38400	6	0.000; 0.010... 9.999 sec	0.1 sec
Baud Rate	Minimum Cycle Time [msec]																		
600	384																		
1200	192																		
2400	96																		
4800	48																		
9600	24																		
19200	12																		
38400	6																		
5-770d	<p>Serial Mode:</p> <p>Operation according to communication profile (see 5.5.1) Transmission of string type 1 (see 5.5.2) Transmission of string type 2 (see 5.5.2)</p>	<table border="1"> <tr><td>PC</td><td>(0)</td></tr> <tr><td>Print 1</td><td>(1)</td></tr> <tr><td>Print 2</td><td>(2)</td></tr> </table>	PC	(0)	Print 1	(1)	Print 2	(2)	PC										
PC	(0)																		
Print 1	(1)																		
Print 2	(2)																		
5-Code	<p>Serial Register-Code:</p> <p>Specifies the register code of the data to be transmitted. The most important register codes are the actual display value and the serial Set/Reset command code</p> <table border="1"> <thead> <tr> <th>Register</th> <th>S-Code</th> <th>ASCII</th> </tr> </thead> <tbody> <tr> <td>Actual display value</td> <td>101</td> <td>: 1</td> </tr> <tr> <td>Activate SET /RESET</td> <td>60</td> <td>6 0</td> </tr> </tbody> </table>	Register	S-Code	ASCII	Actual display value	101	: 1	Activate SET /RESET	60	6 0	100 ... 120	101							
Register	S-Code	ASCII																	
Actual display value	101	: 1																	
Activate SET /RESET	60	6 0																	

*) OS only with DX348

5.5.1. PC-Mode

Communication with PC - Mode allows free readout of all parameters and registers of the unit. The subsequent example shows the details of communication for serial readout of the actual display value.

This is the general format of a serial request string :

EOT	AD1	AD2	C1	C2	ENQ
EOT = Control character (Hex 04)					
AD1 = Unit address, High Byte					
AD2 = Unit address, Low Byte					
C1 = Register code, High Byte					
C2 = Register code, Low Byte					
ENQ = Control character (Hex 05)					

Example: Request for the actual display value from unit number 11:

ASCII-Code:	EOT	1	1	:	1	ENQ
Hexadecimal:	04	31	31	3A	31	05
Binary:	0000 0100	0011 0001	0011 0001	0011 1010	0011 0001	0000 0101

Upon correct request the unit will respond as shown on the right. Leading zeros will be suppressed.
BCC represents a block check character generated from an Exclusive-OR of all characters from C1 through ETX (inclusively)

STX	C1	C2	x x x x x x x	ETX	BCC
STX = Control character (Hex 02)					
C1 = Register code, High Byte					
C2 = Register code, Low Byte					
x x x x x = Register data					
ETX = Control character (Hex 03)					
BCC = Block check character					

With incorrect request strings, the unit only responds STX C1 C2 EOT or just NAK.

Provided the actual display value of the unit would be "-180" (example), the full response of the unit would be as shown below:

ASCII	STX	:	1	-	1	8	0	ETX	BCC
Hex	02	3A	31	2D	31	38	30	03	1C
Binary	0000 0010	0011 1010	0011 0001	0010 1101	0011 0001	0011 1000	0011 0000	0000 0011	0001 1100

Again BCC represents the block check character formed from the Exclusive-OR of all characters from C1 through ETX

Units with serial link also allow setting or resetting the counter by serial command (similar to the external input or front key function). To activate the Reset command, please write "1" to register code "60". To release the Reset command again, write "0" to the same register.

The following strings show how to set or reset a unit with unit No. 11:

Reset ON :

ASCII	EOT	AD1	AD2	STX	C1	C2	Data	ETX	BCC
Hex	04	31	31	02	36	30	31	03	34
Binary	0000 0100	0011 0001	0011 0001	0000 0010	0011 0110	0011 0000	0011 0001	0000 0011	0011 0100

Reset OFF :

ASCII	EOT	AD1	AD2	STX	C1	C2	Data	ETX	BCC
Hex	04	31	31	02	36	30	30	03	35
Binary	0000 0100	0011 0001	0011 0001	0000 0010	0011 0110	0011 0000	0011 0000	0000 0011	0011 0101

For more details about serial communication please refer to the separate document "SERPRO"

5.5.2. Printer-Mode

The Printer Mode allows cyclic or manual activation of transmissions of the specified register data. The corresponding register can be specified by means of parameter „S-Code“.

Another parameter named „S-mod“ allows selection between two different string types:

„S-mod“	Transmission String Type									
„Print1“	Space	Sign	Data						Line feed	Carriage return
		+/-	X	X	X	X	X	X	LF	CR
„Print2“	Sign	Data						Carriage return		
	+/-	X	X	X	X	X	X	CR		

The mode of activation of serial transmissions can be determined as follows:

Cyclic (timed) transmissions:	<p>Set the Serial Timer to any value ≥ 0.010 sec. Select the desired string type by parameter "S-mod"</p> <p>After exit from the menu the timed transmissions will start automatically</p>
Manual activation of transmissions	<p>Set the Serial Timer to 0.000. Select the desired string type by parameter "S-mod"</p> <p>After exit from the menu a transmission can be activated at any time by shortly pressing the ENTER key</p>

6. Special Functions

6.1. Linearization

This function allows converting a non-linear input signal into a linear presentation or vice-versa. There are 16 interpolation points available, which can be freely arranged over the whole measuring range in any distance. Between two points the unit automatically will interpolate straight lines.

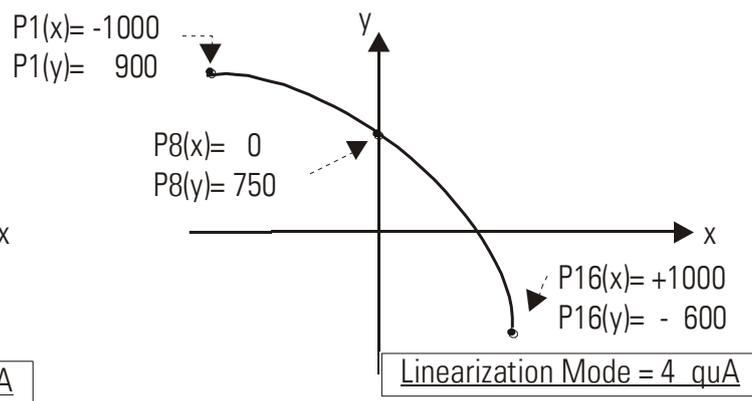
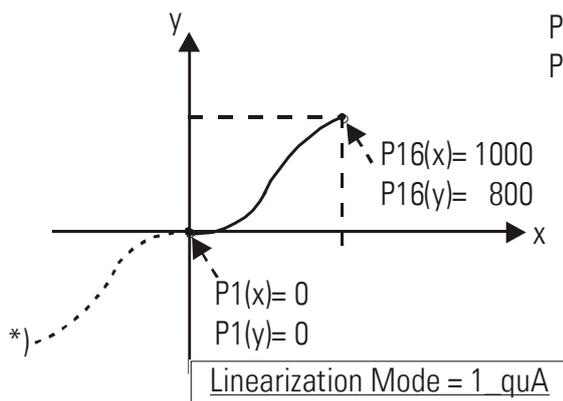
It is advisable to set many points into areas with strong bending, and to use only a few points in areas with little bending. „Linearisation Mode“ has to be set to either „1-quA“ or „4-quA“ to enable the linearization function (see subsequent drawing).

Parameters P01_x to P16_x select 16 x- coordinates, representing the display values which the unit would normally show in the display. With parameters P01_y to P16_y you can specify, which values you would like to display instead of the corresponding _x values.

This means e.g. that the unit will replace the previous P02_x value by the new P02_y value.



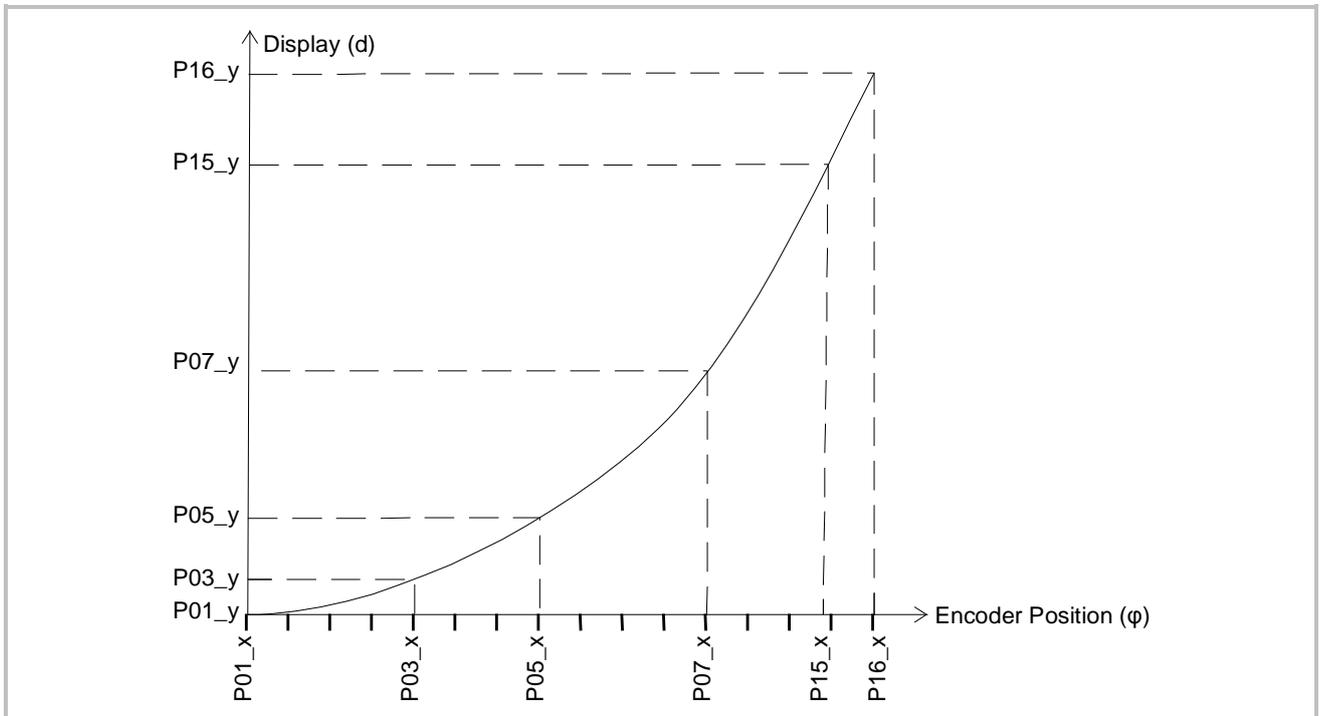
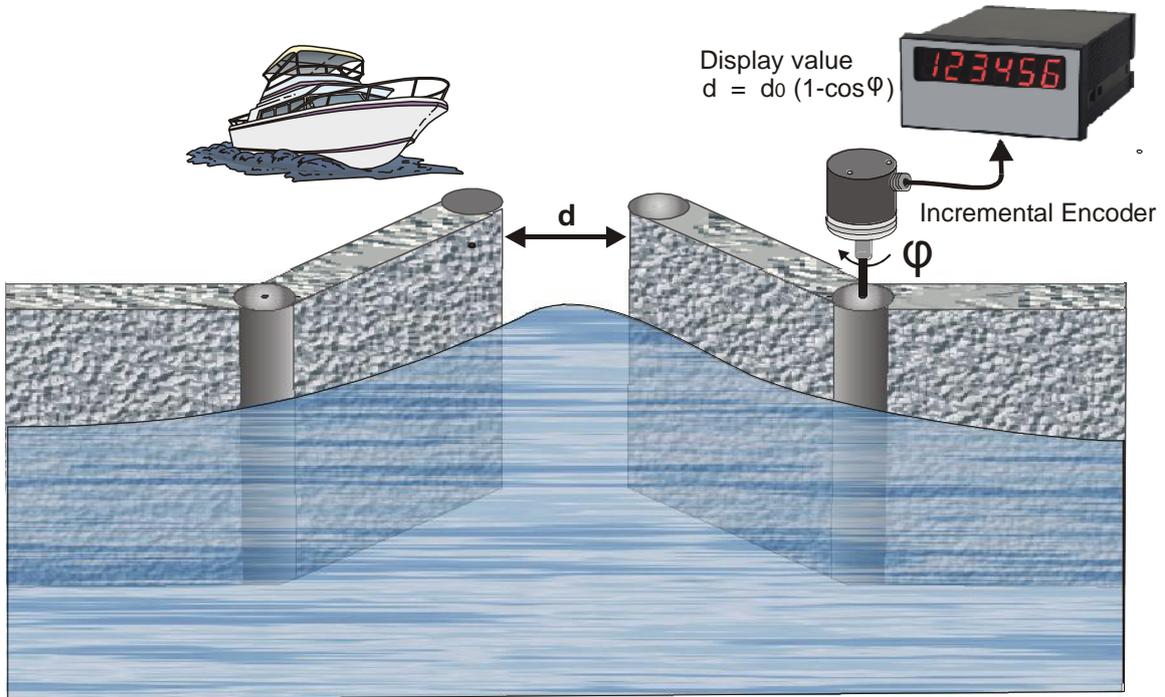
- With respect to the consistency of the linearization, the x- registers have to use continuously increasing values, e.g. the x- registers must conform to the constraint $P01_X < P02_X < \dots < P15_X < P16_X$.
- Independent of the selected linearization mode, the possible setting range of all registers P01_x, P01_y, ..., P16_x, P16_y is always -199999 ... 999999
- With measuring values lower than P01_x the display will always be P01_y
- With measuring values higher than P16_x, the display will always be P16_y.



*.) Mirror of positive range

Application Example:

The picture below shows a Watergate where the opening is picked up by means of an incremental encoder. We would like to display the clearance of the gate "d", but the existing encoder information is proportional to the angular information ϕ .



6.2. Manual Input or „Teaching“ of the Interpolation Points

Interpolation points to form the linearization curve can be entered one after each other, using the same procedure as for all other numeric parameters. This means you will have to enter all parameters P01_x to P16_x and P01_y to P16_y manually by keypad.



During manual input of interpolation points the unit will not examine the settings P01_x to P16_x. Therefore the operator is responsible for observation of the constraint $P01_X < P02_X < \dots < P15_X < P16_X$.

In most cases it should however be much more convenient to use the Teach function. For this method we have to move the encoder, step by step, from one interpolation point to the next. Every time we enter the desired display value by keypad.

How to use the Teach Function:

- Please select the desired range of linearization (see [5.1](#)).
- Hold down the “Cmd” key for 3 seconds, until the display shows “tEACH”. Now the unit has switched over to the Teach mode. To start the teach procedure please press again “Cmd” within the next 10 seconds. The display will then show “P01_X”.
- With respect to the consistency required for linearization, all parameters from P01_X to P16_Y will first be overwritten by suitable initial values. Initial values for „P01_X” and „P01_Y” are -199999 and all other values will start with 999999.
- Press once more “Cmd” to display the actual encoder position. Then move the encoder to the first of the desired interpolation points
- When you read the x-value of your first interpolation point in the display, press “Cmd” again. This will automatically store the actual display value to the P01_x register. For about 1 second you will read “P01_y ” on the display, followed by the same reading again that has been stored previously
- This display value now can be edited like a regular parameter, and you can change it to the desired P01_y value
- When you read the desired P01_y value in your display, store it by pressing “Cmd” again. This will automatically cycle the display to the next interpolation point P02_x.
- Once we have reached and stored the last interpolation points P16_x/y, the routine will restart with P01_x again. You are free to double-check your settings once more or to make corrections.
- To conclude the Teach procedure, keep ENTER down for about 2 seconds. In the display you will read “StOP” for a short time, and then the unit returns to the normal operation. At the same time all linearization points have been finally stored.

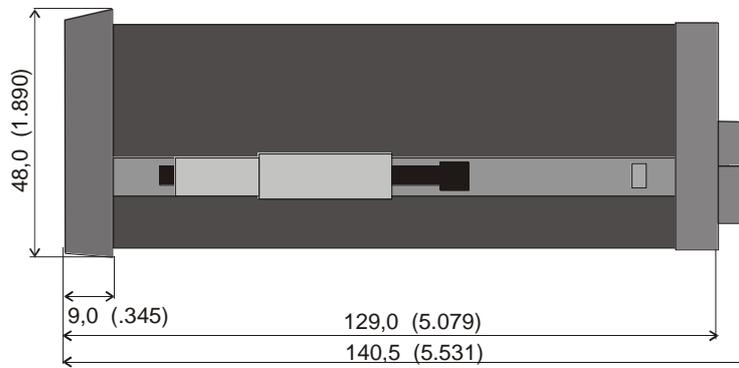
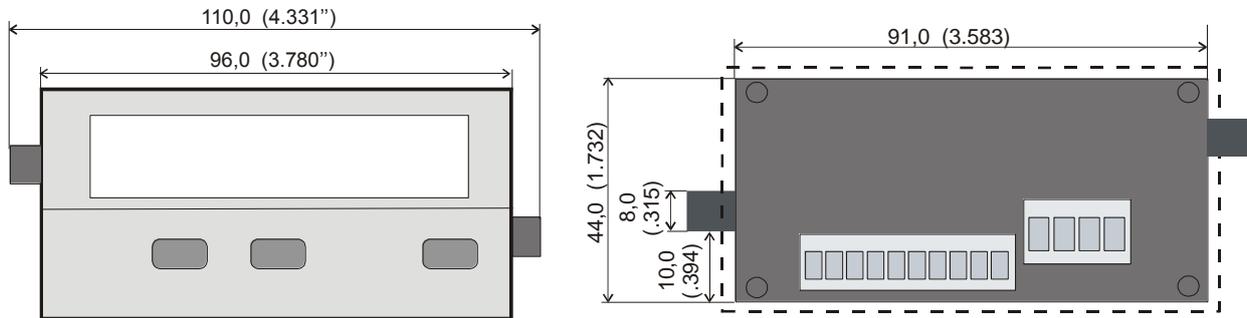


- The unit will examine the constraint valid for the x-values of interpolation points. Every interpolation point must be higher than its preceding point. Where this constraint is breached, all 6 decimal points will blink automatically as a warning. Pressing the CMD key will not store the illegal value, but result in an error text "E.r.r.-.L.O."
- To exit the teach mode again, you have the following two possibilities:
 1. Press the enter key for 2 seconds. On the display you will read "StOP" for a short time, and then the unit will switch back to the normal mode.
 2. Just do nothing. After 10 seconds the unit will switch back to the normal mode automatically.

In both cases the parameters of linearization P01_X to P16_Y will not change.

7. Technical Appendix

7.1. Dimensions



Panel cut out: 91 x 44 mm (3.583 x 1.732")

7.2. Technical Specifications

Power supply:	Input voltage(AC): 115 / 230 VAC (+/- 12.5 %) Power consumption: 7.5 VA Input voltage (DC): 24 VDC (17 ... 30 VDC) Protection circuit (DC): reverse polarity protection Ripple (DC): ≤ 10 % at 24 VDC Consumption: 100 mA at 24 VDC / 80 ... 150 mA at 17... 30 VDC (with an unloaded encoder supply) Connections: AC: screw terminal, 2.5 mm ² / AWG 14 DC: screw terminal, 1.5 mm ² / AWG 16
Encoder supply:	Output voltage: 24 VDC +/- 15 % (with AC supply) 5 VDC (with option TTLIN1) Output current: max. 150 mA (with AC and DC supply)
Incremental inputs:	Number of inputs: 3 x PNP/NPN/Namur Signal levels: HTL (standard): LOW 0 ... 3.5 V, HIGH 9 ... 30 V TTL (option TTLIN1): CMOS, LOW 0 ... 0.8 V, HIGH 3.6 ... 5 V Channels: A, B (pulses) und C (reset signal), Frequency: max. 100 kHz (counter mode) /max. 15 kHz (all other modes) reset input C: 1 kHz (pulse time min. 500 μs) Consumption: 5.1 mA at 24 V (R _i ≈ 4.7 kOhm) Connections: screw terminal, 1.5 mm ² / AWG 16
Accuracy:	Frequency measurement: +/- 100 ppm +/- 1 digit
Refreshment time:	Display: approx. 7 ms (tachometer mode 330 ms)
Analog output (DX346):	Volt output: +/- 10 V, max. 2 mA mA output: 0 ... 20 mA / 4 ... 20 mA (burden: max. 270 Ohm) Resolution: 14 Bit + sign Accuracy: 0.1 % Reaction time: depends on selected operation mode
Transistor outputs (DX347):	Number of outputs: 2 x PNP Signal level: 5 ... max. 35 V Output current: max. 150 mA Connections: screw terminal, 1.5 mm ² / AWG 16
Serial interface (DX348):	Format: RS232, switchable to RS485 (2-conductors) Baud rates (selectable): 600, 1200, 2400, 4800, 9600, 19200, 38400 Baud Operation modes: PC or printer mode Connections: screw terminal, 1.5 mm ² / AWG 16
Display:	Type: 6 Digit LED display Characteristic: high-efficiency orange, 15 mm / 0.59"
Housing:	Type: Norly UL94 – V-0 Material: plastic Mounting: panel Dimensions: cut out (w x h): 91 x 44 mm / 3.583 x 1.7323 inch outer dimensions (w x h x d): 110 x 48 x 140 mm / 4.331 x 1.889 x 5.511 inch Protection class: front: IP 65 / rear: IP20 Weight: approx. 450 g
Ambient temperature:	Operation: 0 °C ... +45 °C / +32 ... +113 °F (not condensing) Storage: -25 °C ... +70 °C / -13 ... +158 °F (not condensing)
Failure rate:	MTBF in years DX345: 96.6 a, DX346: 79.6 a, DX347: 84.3 a, DX348: 89.0 a (long-term usage at 60 °C / 140 °F):
Conformity & standards:	EMC 2004/108/EC: EN 61000-6-2, EN 61000-6-3, EN 61000-6-4 LV 2006/95/EC: EN 61010-1 Guideline 2011/65/EU: RoHS-conform

7.3. Parameter-List

7.3.3. General

Description	Text	Min. Value	Max. Value	Default Value	Positions.	Characters	Serial Code
Unit Type	tYPE	0	4	0	1	0	00
Characteristic	CHAr	0	1	1	1	0	01
Brightness	briGht	0	4	0	1	0	02
Code	CodE	0	2	0	1	0	03
Frequency (Hz)	FrEqu	1	25000	1000	5	0	04
Display Value	diSPL	1	99999	1000	5	0	05
Decimal point	dPoint	0	5	3	1	0	06
Wait Time (sec)	L(Ait	1	999	10	3	1	07
Average Filter	FiLtEr	0	4	0	1	0	08
Display Format	diSFor	0	3	0	1	0	09
Frequency (Hz)	FrEqu	1	25000	100	5	0	10
Display Value	diSPL	1	999999	100	6	0	11
Wait Time (sec)	L(Ait	1	999	50	3	1	12
Average Filter	FiLtEr	0	4	0	1	0	13
Base	bASE	0	6	0	1	0	14
Start / Stop	StArt	0	3	1	1	0	15
Auto Reset	rESEt	0	1	0	1	0	16
Latch Function	LAtch	0	1	0	1	0	17
Count Mode	n)odE	0	5	3	1	0	18
Factor	FActor	1	99999	10000	5	4	19
Set Value	SEt	-199999	999999	0	86	0	20
Reset / Set	rESEt	0	3	3	1	0	21
Decimal point	dPoint	0	5	0	1	0	22
Measuring Time (sec)	tin)E	1	999999	1000	6	3	23
Display Value	diSPL	1	999999	1000	6	0	24
Decimal point	dPoint	0	5	0	1	0	25
Wait Time (s)	L(Ait	0	999	100	3	1	26

7.3.4. Linearization

Description	Text	Min. Value	Max. Value	Default Value	Positions.	Characters	Serial Code
L_Mode	LrnodE	0	2	0	1	0	D2
P1(x)	P01_H	-199999	999999	999999	86	0	A0
P1(y)	P01_Y	-199999	999999	999999	86	0	A1
P2(x)	P02_H	-199999	999999	999999	86	0	A2
P2(y)	P02_Y	-199999	999999	999999	86	0	A3
P3(x)	P03_H	-199999	999999	999999	86	0	A4
P3(y)	P03_Y	-199999	999999	999999	86	0	A5
P4(x)	P04_H	-199999	999999	999999	86	0	A6
P4(y)	P04_Y	-199999	999999	999999	86	0	A7
P5(x)	P05_H	-199999	999999	999999	86	0	A8
P5(y)	P05_Y	-199999	999999	999999	86	0	A9
P6(x)	P06_H	-199999	999999	999999	86	0	B0
P6(y)	P06_Y	-199999	999999	999999	86	0	B1
P7(x)	P07_H	-199999	999999	999999	86	0	B2
P7(y)	P07_Y	-199999	999999	999999	86	0	B3
P8(x)	P08_H	-199999	999999	999999	86	0	B4
P8(y)	P08_Y	-199999	999999	999999	86	0	B5
P9(x)	P09_H	-199999	999999	999999	86	0	B6
P9(y)	P09_Y	-199999	999999	999999	86	0	B7
P10(x)	P10_H	-199999	999999	999999	86	0	B8
P10(y)	P10_Y	-199999	999999	999999	86	0	B9
P11(x)	P11_H	-199999	999999	999999	86	0	C0
P11(y)	P11_Y	-199999	999999	999999	86	0	C1
P12(x)	P12_H	-199999	999999	999999	86	0	C2
P12(y)	P12_Y	-199999	999999	999999	86	0	C3
P13(x)	P13_H	-199999	999999	999999	86	0	C4
P13(y)	P13_Y	-199999	999999	999999	86	0	C5
P14(x)	P14_H	-199999	999999	999999	86	0	C6
P14(y)	P14_Y	-199999	999999	999999	86	0	C7
P15(x)	P15_H	-199999	999999	999999	86	0	C8
P15(y)	P15_Y	-199999	999999	999999	86	0	C9
P16(x)	P16_H	-199999	999999	999999	86	0	D0
P16(y)	P16_Y	-199999	999999	999999	86	0	D1

7.3.5. Analog Output (DX 346)

Description	Text	Min. Value	Max. Value	Default Value	Positions.	Characters	Serial Code
Analog Start	An-bEG	-199999	999999	0	86	0	31
Analog End	An-End	-199999	999999	10000	86	0	32
Analog Mode	A-CHAR	0	3	1	1	0	33
Offset	OFFSEt	-9999	9999	0	84	3	34
Gain	GAin	0	9999	1000	4	2	35

7.3.6. Preselection's (DX 347)

Description	Text	Min. Value	Max. Value	Default Value	Positions.	Characters	Serial Code
Preselection Value 1	PrES1	-199999	999999	10000	86	0	27
Preselection Value 2	PrES2	-199999	999999	5000	86	0	28
Preselection Mode 1	CHAR1	0	5	0	1	0	29
Preselection Mode 2	CHAR2	0	5	0	1	0	30
Hysteresis 1	HYSt1	0	99999	0	5	0	31
Hysteresis 2	HYSt2	0	99999	0	5	0	32

7.3.7. Serial interface (DX 348)

Description	Text	Min. Value	Max. Value	Default Value	Positions.	Characters	Serial Code
Serial Timer (s)	S-tin)	0	9999	100	4	3	38
Serial Mode	S-n)od	0	2	0	1	0	39
Serial Code	S-CodE	100	120	101	3	0	40
Serial Unit Nr	S-Unit	0	99	11	2	0	90
Serial Format	S-Forn	0	9	0	1	0	92
Serial Baudrate	S-bAUd	0	6	0	1	0	91

7.4. Commissioning Form

Date:	Software:
Operator:	Serial number:

Basic settings:	Unit Type:	NPN /PNP:
	Brightness:	Code:
	Linearization Mode(*):	
Additional DX346	Analog Mode:	Offset
	Gain	
Additional DX347	Preselection Mode 1:	Preselection Mode 2:
	Hysteresis 1:	Hysteresis 2:
Additional DX348	Serial Unit Number:	Serial Format:
	Serial Baud:	

(*) Appears only with modes "RPM" and "Count"

Operation Mode (Type)		
RPM	Frequency (Hz):	Display Value:
	Decimal Point:	Wait Time(sec):
	Average Filter:	
Time	Display Format:	Frequency (Hz):
	Display Value:	Wait Time (sec):
	Average Filter:	
Timer	Base:	Start/Stop:
	Auto Reset:	Latch Function:
Count	Count Mode:	Factor:
	Set Value:	Reset/Set:
	Decimal Point:	
Speed	Time (sec):	Display Value:
	Decimal Point:	Wait Time (sec):

Additional parameters:		
Additional DX346	Analog Begin:	Analog End:
Additional DX347	Preselection 1:	Preselection 2:
Additional DX348	Serial Timer (sec):	Serial Mode:
	Serial Code:	

<u>Linearization</u> (*)			
P1(x):	P1(y):	P9(x):	P9(y):
P2(x):	P2(y):	P10(x):	P10(y):
P3(x):	P3(y):	P11(x):	P11(y):
P4(x):	P4(y):	P12(x):	P12(y):
P5(x):	P5(y):	P13(x):	P13(y):
P6(x):	P6(y):	P14(x):	P14(y):
P7(x):	P7(y):	P15(x):	P15(y):
P8(x):	P8(y):	P16(x):	P16(y):

(*) Appears only with Modes "RPM" and "Count" if Linearization has been enabled

